A Study on Predictive Deep Reinforcement Learning for **Isolated Intersection Signal Control**

予測深層強化学習の単独交差点信号制御への適用性に関する一考察

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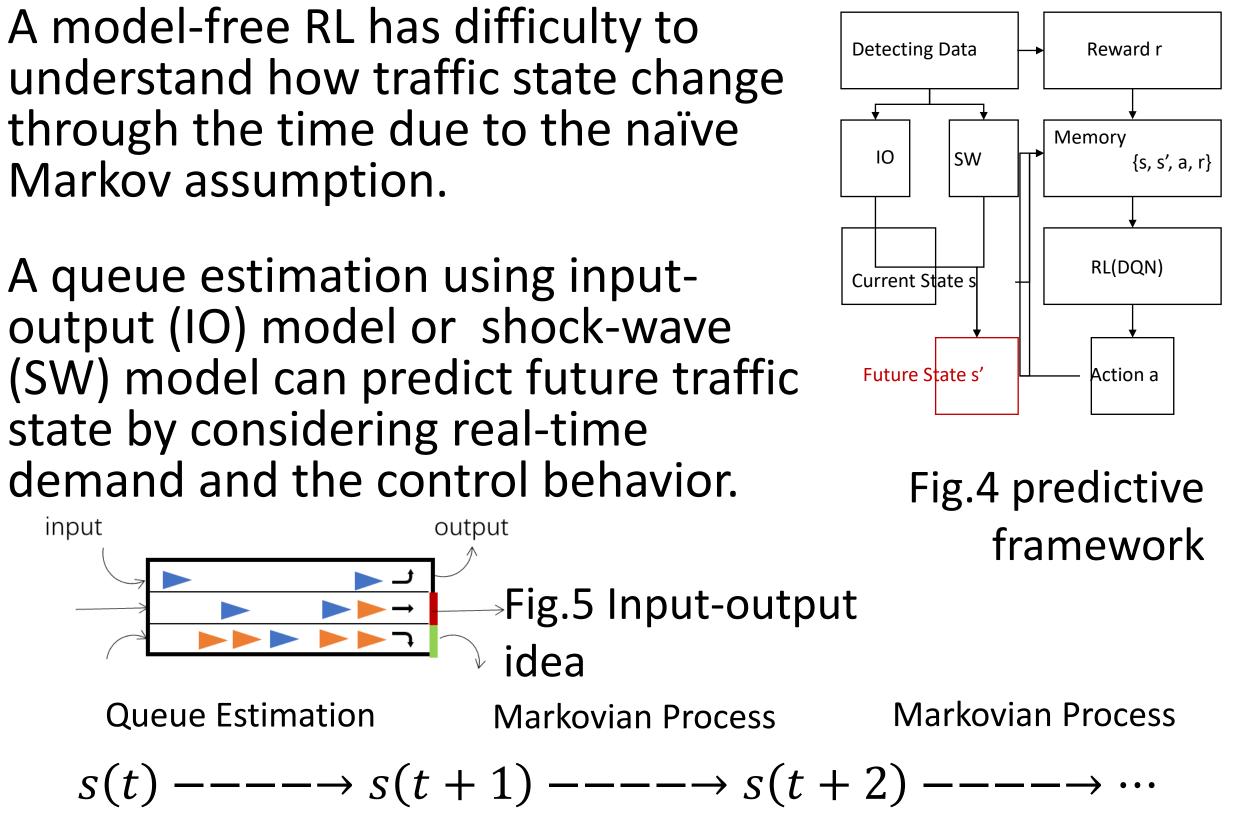
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1.Traffic Signal Control (TSC)

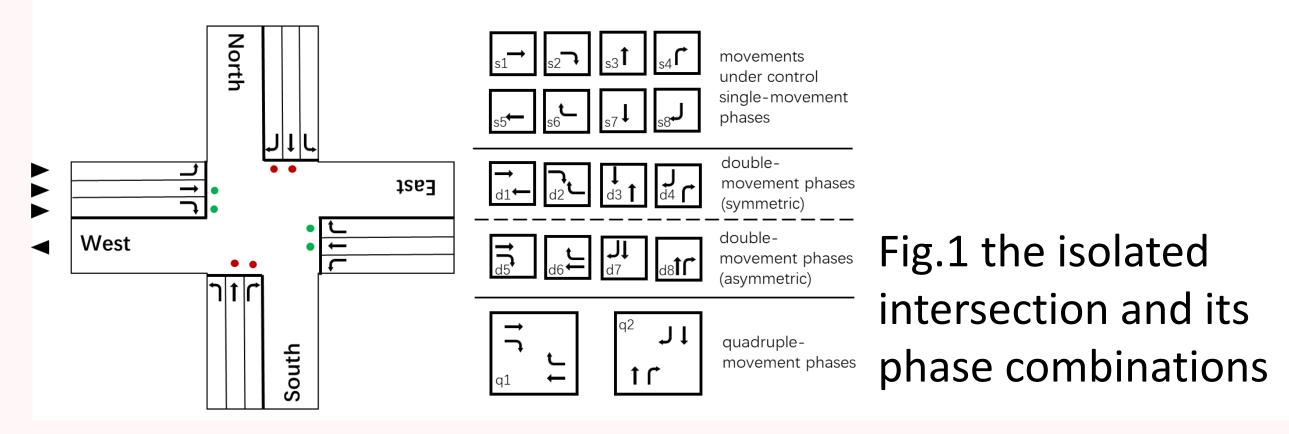
- Basic idea \bullet
 - Separate vehicle from different direction temporally to ensure safety. Bring extra waiting time to road users.
- Approach
 - Produce phases and corresponding duration for

3.Predictive RL with Queue Estimation

- A model-free RL has difficulty to through the time due to the naïve Markov assumption.
- A queue estimation using inputoutput (IO) model or shock-wave





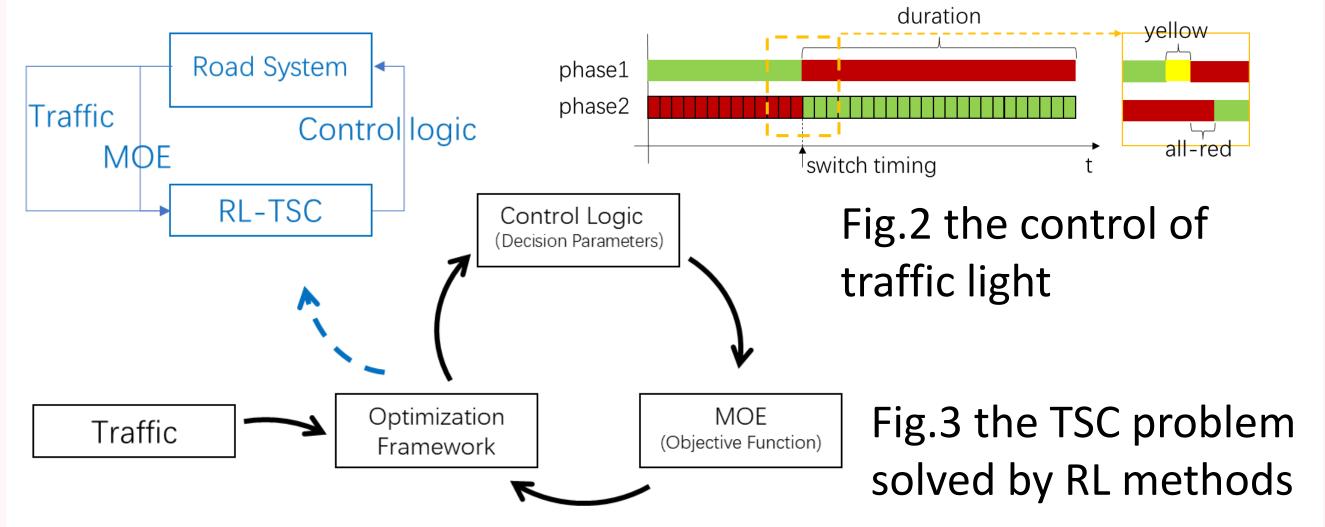


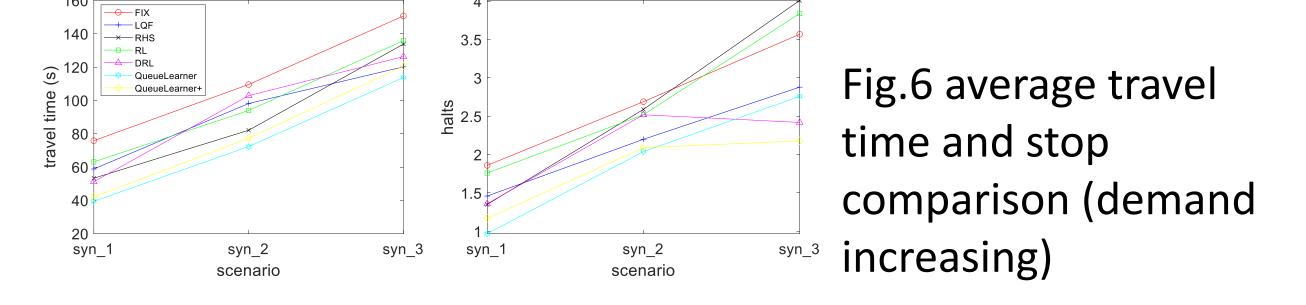
2.Reinforcement Learning(RL) Modelling

- The RL is an autonomous control method to take responsive actions (a) with observed (s) states. Supposing the effect of actions could be measured as the reward r, the RL only needs to learn action under various states to achieve higher reward.
- TSC problem could be modelled as:
 - States: real time traffic demand (how many vehicle incoming?)

4.Simulation Experiment & Results

- The validation of the proposed method (QueueLearner) is conducted with SUMO (Simulation of Urban MObility).
- Comparison with both traffic engineering methods (FIX, LQF, RHS) and traditional reinforcement (RL, DRL) learning methods.
- Better robustness for demand increasing.
- Action: control logic (which phase to choose?)
- Reward: measure of efficiency (how effective can the vehicles be served?)



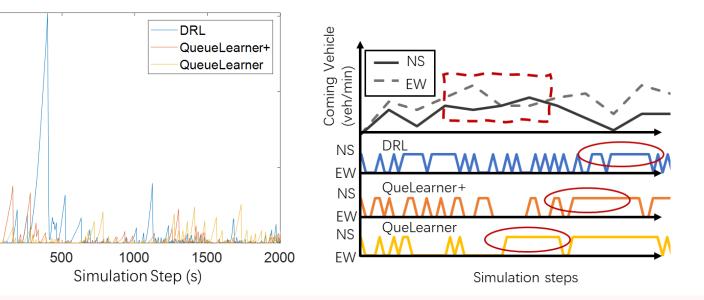


Fast adaption of traffic change than traditional RL

1000

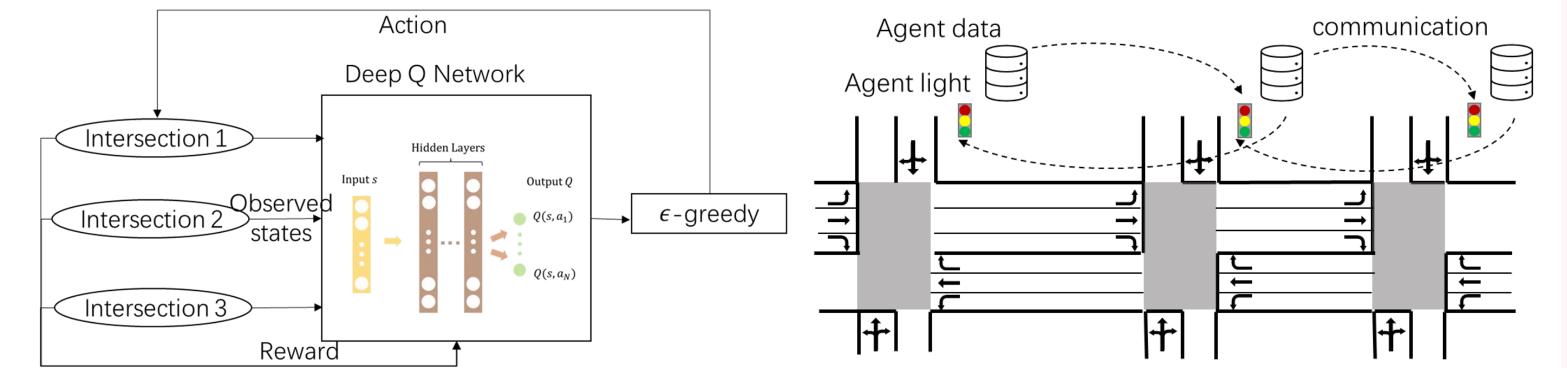
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Fig.7 accumulated waiting time and demand-supply comparison



5.More Related Information

- Coordinated intersections along one artery by communication among decentralized multi-agent RL system. \bullet
 - Share-brain for computational economic
 - Green-wave for less stoppage
- Toward a more general urban road network \bullet
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